

## **GATE 2019** Electrical Engineering Questions

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Newspapers are a constant source of 1. delight and recreation for me. The \_\_\_\_\_ trouble is that I read \_\_\_\_\_ many of them

	,			
Α.	even, too	В.	even,	quite

C. only, quite D. only, too

- 2. The missing number in the given sequence 343,1331,\_\_\_\_, 4913 is A. 2744 B. 2197
  - C. 4096 D. 3375
- The passengers were angry \_\_\_\_\_ 3. \_ the airline staff about the delay.
  - A. towards B. on
  - C. with D. about
- 4. It takes two hours for a person X to mow the lawn. Y can move the same lawn in four hours. How long (in minutes) will it take X and Y, if they work together to move the lawn?

Α.	120	В.	80
C.	60	D.	90

5. I am not sure if the bus that has been booked will be able to \_\_\_\_\_ all the students.

B. deteriorate

A. sit

D. fill C. accommodate

6. Given two sets  $X = \{1, 2, 3\}$  and  $Y = \{2, 3\}$ 3, 4}, we construct a set Z of all possible fractions where the numerators belong to set X and the denominators belong to set Y. The product of element having minimum and maximum values in the set Z is

Α.	3/8	В.	1/12
C.	1/8	D.	1/6

7. The ratio of the number of boys and girls who participated in an examination is 4 : 3. The total percentage of candidates who passed the examination is 80 and the percentage of girls who passed is 90. The percentage of boys who passed is

8. An award-winning study by a group of researchers suggests that men are as prone to buying on impulse as women feel more guilty about shopping.

> Which one of the following statements can be inferred from the given text?

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- A. Some men and women indulge in buying on impulse
- B. Few men and women indulge in buying on impulse
- C. Many men and women indulge in buying on impulse
- D. All men and women indulge in buving on impulse
- 9. How many integers are there between 100 and 1000 all of whose digits are even?
  - A. 100 B. 60
  - C. 90 D. 80
- 10. Consider five people - Mita, Ganga, Rekha, Lakshmi and Sana. Ganga is taller than both Rekha and Lakshmi. Lakshmi is taller than Sana. Mita is taller than Ganga. Which of the following conclusions are true?
  - 1. Lakshmi is taller than Rekha
  - 2. Rekha is shorter than Mita
  - 3. Rekha is taller than Sana
  - 4. Sana is shorter than Ganga
  - A. 1 and 3 B. 1 only
  - C. 2 and 4 D. 3 only

## SECTION : EE ELECTRICAL ENGINEERING

The mean-square of a zero-mean random 1. process is  $\frac{kT}{C}$ , where k is Boltzmann's constant, T is the absolute temperature, and C is capacitance. The standard deviation of the random process is

A. 
$$\frac{\sqrt{kT}}{C}$$
 B.  $\frac{kT}{C}$   
C.  $\sqrt{\frac{kT}{C}}$  D.  $\frac{c}{kT}$ 

2. The characteristic equation of a linear timeinvariant (LTI) system is given by

 $\Delta(s) = s^4 + 3s^3 + 3s^2 + s + k = 0.$ The system is BIBO stable if

A. 
$$0 < k < \frac{12}{9}$$
 B.  $0 < k < \frac{8}{9}$ 

C. k > D. k > 3 3. The inverse Laplace transform of  $H(s) = \frac{s+3}{s^2+2s+1}$  for  $\ge 0$  is

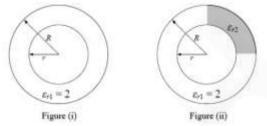
S
$$+2S+1$$
A.  $2te^{-t} + e^{-t}$ B.  $3te^{-t} + e^{-t}$ C.  $3e^{-t}$ D.  $4te^{-t} + e^{-t}$ 



- A 5 kVA, 50 V/100 V, single-phase transformer has a secondary terminal voltage of 95 V when loaded. The regulation of the transformer is
  A. 9%
  B. 4.5%
  C. 1%
  D. 5%
- 5. A three-phase synchronous motor draws 200 A from the line at unity power factor at rated load. Considering the same line voltage and load, the line current at power factor of 0.5 leading is

Α.	400 A	в.	300 A
C.	200 A	D.	100 A

6. A cv-axial cylindrical capacitor shown in Figure (i) has dielectric with relative permittivity  $\varepsilon r 1 = 2$ . When one-fourth portion of the dielectric is replaced with another dielectric of relative permittivity  $\varepsilon r_2$ , as shown to Figure (ii), the capacitance is doubled. The value of  $\varepsilon r_2$  is \_\_\_\_\_.



- The parameter of an equivalent circuit of a three-phase induction motor affected by reducing the rms value of the supply voltage at the rated frequency is
  - A. rotor leakage reactance
  - B. stator resistance
  - C. rotor resistance
  - D. magnetizing reactance
- The output response of a system is denoted as y(t), and its Laplace transform is given by

$$Y(s)=\frac{10}{s(s^2+s+100\sqrt{2})}.$$

The steady state value of y(t) is

A. 
$$10\sqrt{2}$$
 B.  $100\sqrt{2}$   
C.  $\frac{1}{10\sqrt{2}}$  D.  $\frac{1}{100\sqrt{2}}$ 

9. The open loop transfer function of a unity feedback system is given by

$$G(s)=\frac{\pi e^{-0.25s}}{s}.$$

In G(s) plane, the Nyquist plot of G(s) passes through the negative real axis at the point

A. (-0.5, j0)	B. (-1.5, j0)
---------------	---------------

- C. (-1.25, j0) D. (-0.75, j0)
- 10. A current controlled current source (CCCS) has an input impedance of 10  $\Omega$  and output impedance of 100 k $\Omega$ . When this CCCS is used in a negative feedback closed loop with a loop gain of 9, the closed loop output impedance is

A. 100 kΩ B. 1000 kΩ

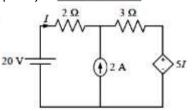
C. 100 Ω D. 10 Ω

11. A six-pulse thyristor bridge rectifier is connected to a balanced three-phase, 50 Hz AC source. Assuming that the DC output current of the rectifier is constant, the lowest harmonic component in the AC input current is

C. 300 Hz D. 250 Hz

150 Hz

 The current I flowing in the circuit shown below in amperes (round off to one decimal place) is \_\_\_\_\_.



13. The partial differential equation

$$\frac{\partial^2 u}{\partial t^2} - c^2 \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) = 0; \text{ where } c \neq 0$$

is known as

- A. Poisson's equation
- B. wave equation
- C. Laplace equation
- D. heat equation
- 14. Which one of the following function is analytic in the region  $|z| \le 1$ ?

A. 
$$\frac{z^2 - 1}{z + 2}$$
  
B.  $\frac{z^2 - 1}{z}$   
C.  $\frac{z^2 - 1}{z - 0.5}$   
D.  $\frac{z^2 - 1}{z - i0.5}$ 

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- 15. If  $f = 2x^3 + 3y^2 + 4z$ , the value of line integral  $\int_c$  grade f. dr evaluated over contour C formed by the segments (-3, -3, 2)  $\rightarrow$  (2, -3, 2)  $\rightarrow$  (2, 6, 2)  $\rightarrow$  (1, 6, -1) is
- Five alternators each rated 5 MVA, 13.2 kV with 25% of reactance on its own base are connected in parallel to a busbar. The short-circuit level in MVA at the busbar is
- 17. Given  $V_{gs}$  is the gate-source voltage,  $V_{ds}$  is the drain voltage, and  $V_{th}$  is threshold voltage of an enhancement type NMOS transistor, the conditions for transistor to be biased in saturation are
  - A.  $V_{gs} > V_{th}$ ;  $V_{ds} \le V_{gs} V_{th}$
  - B.  $V_{gs} < V_{th}$ ;  $V_{ds} \ge V_{gs} V_{th}$
  - C.  $V_{gs} > V_{th}$ ;  $V_{ds} \ge V_{gs} V_{th}$
  - D.  $V_{gs} < V_{th}$ ;  $V_{ds} \le V_{gs} V_{th}$
- 18. The total impedance of the secondary winding, leads, and burden of a 5 A CT is  $0.01 \Omega$ . If the fault current is 20 times the rated primary current of the CT, the VA output of the CT is \_\_\_\_\_.
- 19. The Y<sub>bus</sub> matrix of a two-bus power system having two identical parallel lines connected between them in pu is given as

$$Y_{bus} = \begin{bmatrix} -j8 & j20 \\ j20 & -j8 \end{bmatrix}.$$

The magnitude of the series reactance of each line in pu (round off up to one decimal place) is \_\_\_\_\_.

- 20. The rank of the matrix,  $M = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$ , is
- 21. The symbols, a and T, represent positive quantities, and u(t) is the unit step function. Which one of the following impulse responses is NOT the output of a causal linear time-invariant system?
  A. e<sup>-a(t-T)</sup>u(t)
  B. e<sup>+at</sup>u(t)

C. 
$$1 + e^{-at} u(t)$$
 D.  $e^{-a(t + T)}u(t)$ 

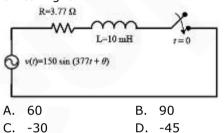
22. A system transfer function is  $2c^2 + bc + c$ 

$$H(s) = \frac{a_1 s^2 + b_1 s + c_1}{a_2 s^2 + b_2 s + c_2}.$$
 If  $a_1 = b_1 = 0$ , and

all other coefficients are positive, the transfer function represents a

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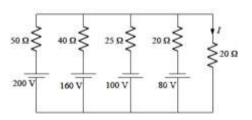
- A. high pass filter
- B. band pass filter
- C. notch filter
- D. low pass filter
- 23. The output voltage of a single-phase full bridge voltage source inverter is controlled by unipolar PWM with one pulse per half cycle. For the fundamental rms component of output voltage to be 75% of DC voltage, the required pulse width in degrees (round off up to one decimal place) is \_\_\_\_\_.
- 24. In the circuit shown below, the switch is closed at t = 0. The value of  $\theta$  in degrees which will give the maximum value of DC offset of the current at the time of switching is



- 25. M is a 2  $\times$  2 matrix with eigenvalues 4 and 9. The eigenvalues of M<sup>2</sup> are
  - A. 2 and 3 B. -2 and 3

C. 16 and 81 D. 4 and 9

- 26. A three-phase 50 Hz, 400 kV transmission line is 300 km long. The line inductance is 1 mH/km per phase, and the capacitance is 0.01  $\mu$ F/km per phase. The line is under open circuit condition at the receiving end and energized with 400 kV at the sending end, the receiving end and energized with 400 kV at the sending end line voltage end line voltage in kV (round off to two decimal places) will be
- 27. The current I flowing in the circuit shown below in amperes is \_\_\_\_\_.





- 28. A 220 V (line), three-phase, Y-connected, synchronous motor has a synchronous impedance of  $(0.25 + j2.5) \Omega$ /phase. The motor draws the rated current of 10 A at 0.8 pf leading. The rms value of line-to-line internal voltage in volts (round off to two decimal places) is
- 29. The closed loop line integral

$$\circ z^{2} z^{3} - dz$$

evaluated counter-clockwise, is

Α. +4j π Β. -4j π

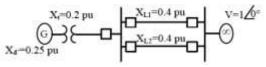
C. + 8j π D. -8j π

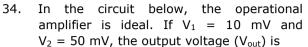
30. The voltage across and the current through a load are expressed as follows

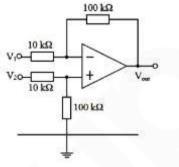
$$v(t) = -170 \sin\left(377t - \frac{\pi}{6}\right) V$$
$$i(t) = 8\cos\left(377t + \frac{\pi}{6}\right) A$$

The average power in watts (round off to one decimal place) consumed by the load is \_\_\_\_\_\_.

- 31. A delta-connected, 3.7 kW, 400 V(line), three-phase, 4-pole, 50-Hz squirrel-cage induction motor has the following equivalent circuit parameters per phase referred to the stator:  $R_1 = 5.39 \Omega$ ,  $R_2 = 5.72 \Omega$ ,  $X_1 = X_2 = 8.22 \Omega$ . Neglect shunt branch in the equivalent circuit. The starting line current in amperes (round off to two decimal places) when it is connected to a 100 V (line), 10 Hz, three-phase AC source is \_\_\_\_\_.
- 32. In a 132 kV system, the series inductance up to the point of circuit breaker location is 50 mH. The shunt capacitance at the circuit breaker terminal is  $0.05 \ \mu$ F. The critical value of resistance in ohms required to be connected across the circuit breaker contacts which will give no transient oscillation is \_\_\_\_\_\_.
- 33. In the single machine infinite bus system shown below, the generator is delivering the real power of 0.8 pu at 0.8 power factor lagging to the infinite bus. The power angle of the generator in degrees (round off to one decimal place) is

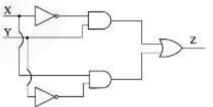






A. 600 mVB. 500 mVC. 400 mVD. 100 mV

 In the circuit shown below, X and Y are digital inputs, and Z is a digital output. The equivalent circuit is a



A. XOR gate B. NAND gate

- C. XNOR gate D. NOR gate
- 36. A 0.1  $\mu$ F capacitor charged to 100 V is discharged through a 1 k $\Omega$  resistor. The time in ms (round off to two decimal places) required for the voltage across the capacitor to drop to 1 V is \_\_\_\_\_.
- A periodic function f(t), with a period of 2π, is represented as its Fourier series,

$$f(t) = a_0 + \sum_{n=1}^{\infty} a_n \cos nt + \sum_{n=1}^{\infty} b_n \sin nt.$$
  
If  
$$(A \sin t, 0 \le t \le \pi)$$

$$f(t) = \begin{cases} f(t) = 0 & \text{if } t < 2\pi \end{cases}$$

the Fourier series coefficients  $a_1 \mbox{ and } b_1 \mbox{ of } f(t) \mbox{ are }$ 

A. 
$$a_1 = 0$$
;  $b_1 = A/\pi$  B.  $a_1 = 0$ ;  $b_1 = \frac{A}{2}$   
C.  $a_1 = \frac{A}{\pi}$ ;  $b_1 = 0$  D.  $a_1 = \frac{A}{2}$ ;  $b_1 = 0$ 

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- If A = 2xi + 3yj + 4zk and u =  $x^2 + y^2 + y^2$ 38. z<sup>2</sup>, then div (u**A**) at (1, 1, 1) is \_\_\_\_
- A moving coil instrument having a 39. resistance of 10  $\Omega$ , gives a full-scale deflection when the current is 10 mA. What should be the value of the series resistance, so that it can be used as a potential voltmeter for measuring difference up to 100 V? 990 Ω

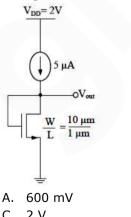
- C. 99 Ω D. 9Ω
- 40. Consider a state-variable model of a system

$$\begin{bmatrix} \vdots & 1\\ \vdots & e & -2\beta \end{bmatrix} \begin{bmatrix} x_1\\ x_2 \end{bmatrix} + \begin{bmatrix} 0\\ \alpha \end{bmatrix} r$$
$$y = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x_1\\ x_2 \end{bmatrix}$$

where y is the output, and r is the input. The damping ratio  $\xi$  and the undamped natural frequency  $\omega_n$  (rad/sec) of the system are given by

A. 
$$\xi = \sqrt{\beta}; \omega_n = \sqrt{\alpha}$$
  
B.  $\xi = \sqrt{\alpha}; \omega_n = \frac{\beta}{\sqrt{\alpha}}$   
C.  $\xi = \frac{\sqrt{\alpha}}{\beta}; \omega_n = \sqrt{\beta}$   
D.  $\xi = \frac{\beta}{\sqrt{\alpha}}; \omega_n = \sqrt{\alpha}$ 

The enhancement type MOSFET in the 41. circuit below operates according to the square law.  $\mu_n C_{ox} = 100 \ \mu A/V^2$ , the threshold voltage  $(V_T)$  is 500 mV. Ignore channel length modulation. The output voltage Vout is

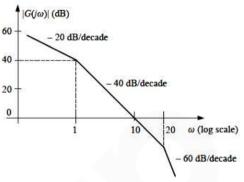


B. 500 mV

C. 2 V

D. 100 mV

The asymptotic Bode magnitude plot of a 42. minimum phase transfer function G(s) is shown below.



Consider the following two statements. Statement I : Transfer function G(s) has three poles and one zero.

Statement II : At very high frequency ( $\omega \rightarrow$ 

$$\infty$$
), the phase angle  $\angle G(j\omega) = -\frac{3\pi}{2}$ .

Which one of the following options is correct?

- A. Both the statements are true.
- B. Both the statements are false.
- C. Statement I is false and statement II is true.
- D. Statement I is true and statement II is false.
- 43. A single-phase transformer of rating 25 kVA, supplies a 12 kW load at power factor of 0.6 lagging. The additional load at unity power factor in kW (round off to two decimal places) that may be added before this transformer exceeds its rated kVA is

44. Consider a 2  $\times$  2 matrix M = [v<sub>1</sub> v<sub>2</sub>], where.  $v_1$  and  $v_2$  are the column vectors.

suppose  $M^{-1} = \begin{vmatrix} u_1^T \\ u_2^T \end{vmatrix}$ , where  $u_1^T$  and  $u_2^T$  are

the row vectors. Consider the following statements :

Statement 1 :  $u_1^T v_1 = 1$  and  $u_2^T v_2 = 1$ 

Statement 2 :  $u_1^T v_1 = 0$  and  $u_2^T v_1 = 0$ 

Which of the following options is correct? A. Both the statements are false

B. Statement 2 is true and statement 1 is false

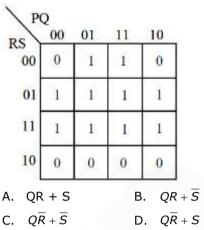
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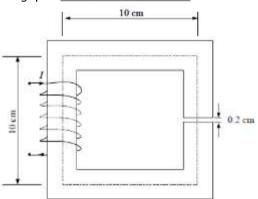
- C. Statement 1 is true and statement 2 is false
- D. Both the statements are true
- 45. A single-phase fully-controlled thyristor converter is used to obtain an average voltage of 180 V with 10 A constant current to feed a DC load. It is fed from single-phase AC supply of 230 V, 50 Hz. Neglect the source impedance. The power factor (round off to two decimal places) of AC mains is \_\_\_\_\_.
- 46. A DC-DC buck converter operates in continuous conduction mode. It has 48 V input voltage, and it feeds a resistive load of 24  $\Omega$ . The switching frequency of the converter is 250 Hz. If switch-on duration is 1 ms, the load power is

A. 12 W B. 6 W C. 24 W D. 48 W

- 47. In a DC-DC boost converter, the duty ratio is controlled to regulate the output voltage at 48 V. The input DC voltage is 24 V. The output power is 120 W. The switching frequency is 50 kHz. Assume ideal components and a very large output filter capacitor. The converter operates at the boundary between continuous and discontinuous conduction modes. The value of the boost inductor (in μH) is \_\_\_\_\_.
- 48. A 220 V DC shunt motor takes 3 A at noload. It draws 25 A when running at fullload at 1500 rpm. The armature and shunt resistances are 0.5  $\Omega$  and 220  $\Omega$ , respectively. The no-load speed in rpm (round off to two decimal places) is
- 49. A fully-controlled three-phase bridge converter is working from a 415 V, 50 Hz AC supply. It is supplying constant current of 100 A at 400 V to a DC load. Assume large inductive smoothing and neglect overlap. The rms value of the AC line current in amperes (round off to two decimal places) is \_\_\_\_\_.
- 50. The output expression for the Karnuaugh map shown below is



- 51. The probability of a resistor being defective is 0.02. There are 50 such resistors in a circuit. The probability of two or more defective resistors in the circuit (round off to two decimal places) is
- 52. The magnetic circuit shown below has uniform cross-sectional area and air gap of 0.2 cm. The mean path length of the core is 40 cm. Assume that leakage and fringing fluxes are negligible. When the core relative permeability is assumed to be infinite, the magnetic flux densitv computed in the air gap is 1 tesla. With same Ampere-turns, if the core relative permeability is assumed to be 1000 (linear), the flux density in tesla (round off to three decimal places) calculated in the air gap is



53. A 30 kV, 50 Hz, 50 MVA generator has the positive, negative, and zero sequence reactances of 0.25 pu, 0.15 pu, and 0.05 pu, respectively. The neutral of the generator is grounded with a reactance so that the fault current for a bolted LG fault

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and that of a bolted three-phase fault at the generator terminal are equal. The value of grounding reactance in ohms (round off to one decimal place) is

54. The line currents of a three-phase four wire system are square waves with amplitude of 100 A. These three currents are phase shifted by 120° with respect to each other. The rms value of neutral current is

C. 100 A D. 
$$\frac{100}{\sqrt{3}}$$

55. The transfer function of a phase lead compensator is given by

$$D(s) = \frac{3\left(s + \frac{1}{3T}\right)}{\left(s + \frac{1}{T}\right)}.$$

The frequency (in rad/sec), at which  $\angle D(j\omega)$  is maximum, is

A. 
$$\sqrt{3T}$$
B.  $\sqrt{3T^2}$ C.  $\sqrt{\frac{1}{3T^2}}$ D.  $\sqrt{\frac{1}{T^2}}$ 

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