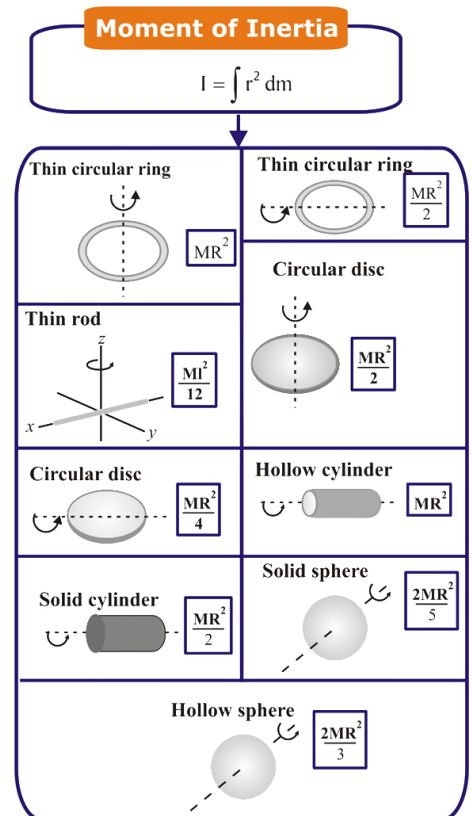


Rotational Motion - I

Rotational Motion

Rotational Motion

1. Moment of Inertia.
2. Calculation of Torque and Angular Momentum
3. Fixed Axis Rotation



Angular Momentum about a point

$$\vec{L} = \vec{r} \times \vec{P}$$

$$L = r_{\perp} \cdot P$$

$$L = r P_{\perp}$$

Torque about a point

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\tau = r_{\perp} F$$

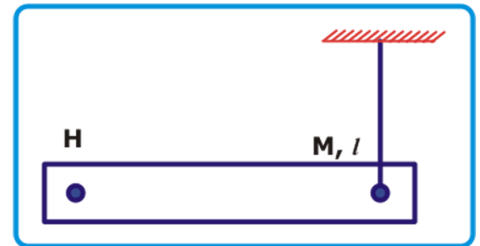
$$\tau = r F_{\perp}$$

Torque about an axis

- ❖ Component of torque, about a point on the axis, along the axis.
- ❖ F_{axial} and F_{radial} will not give any torque about an axis.

Rotational Equilibrium

$$\sum \tau_{\text{axis}} = 0$$



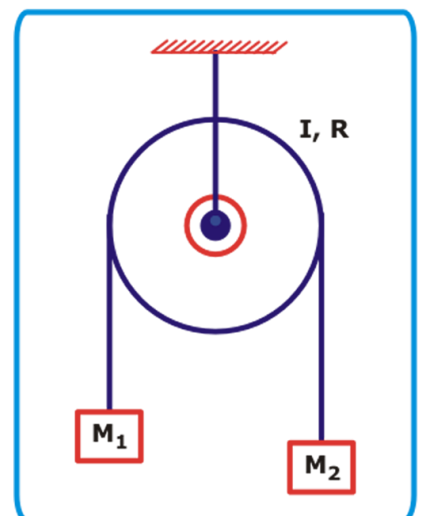
Fixed Axis Rotation

$$\tau_H = I_H \alpha$$

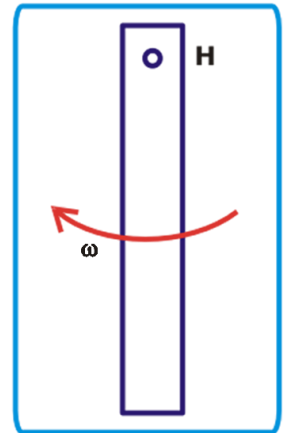
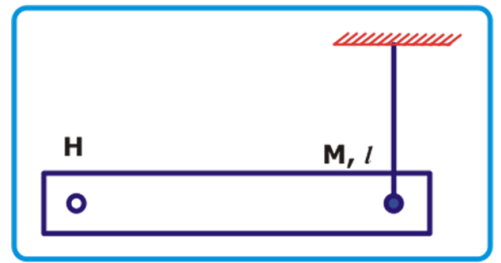
$$L_H = I_H \omega$$

$$R_{\text{KE}} = \frac{1}{2} I_H \omega^2$$

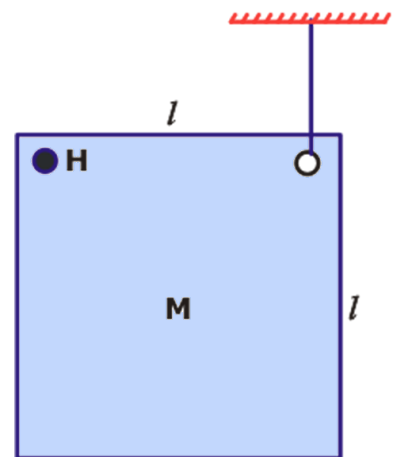
Fixed Axis Rotation



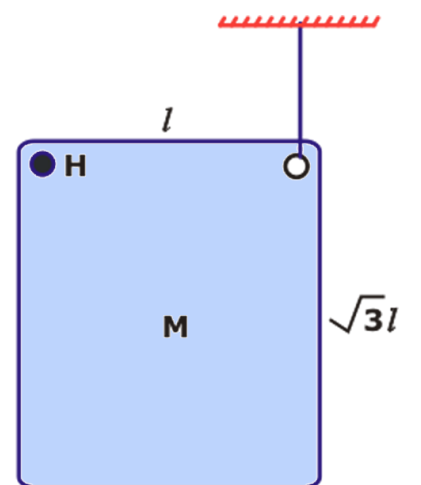
Fixed Axis Rotation



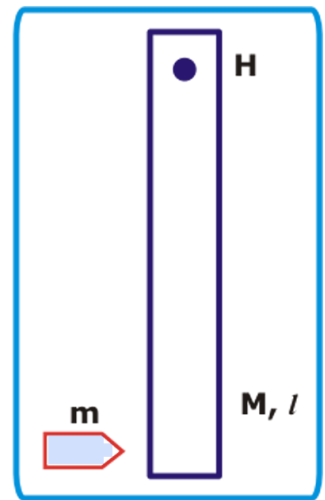
Fixed Axis Rotation



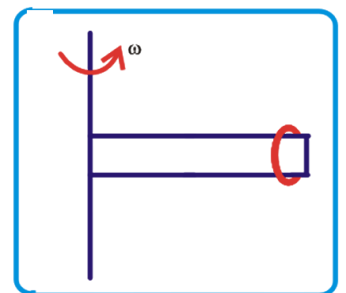
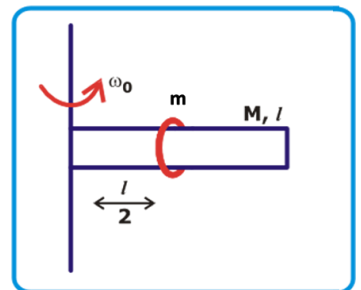
Fixed Axis Rotation



Conservation of Angular Momentum



Conservation of Angular Momentum



Conservation of Angular Momentum

