

1. Ans. C.

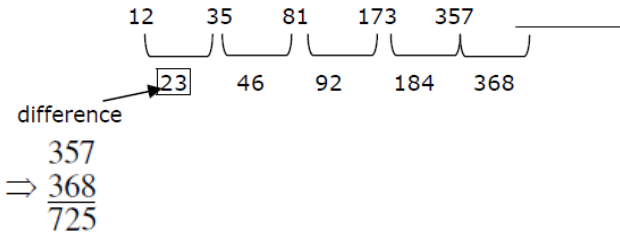
2. Ans. D.

3. Ans. B.

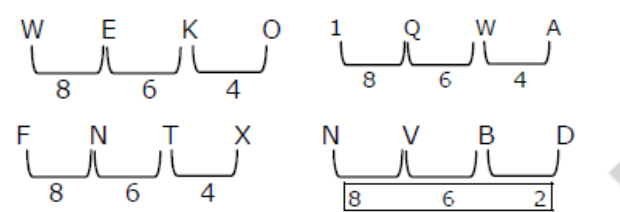
4. Ans. A.

If the standard deviation is less, there will be less deviation or batsman is more consistent

5. Ans. B.



6. Ans. D.



Difference of position: D

7. Ans. B.

Resident female in between 8 to 10 lakhs haven't been mentioned.

8. Ans. D.

For a train to cross a person, it takes 60 seconds for its 280m. So, for second 60 seconds. Total distance travelled should be 840. Including 280 train length, length of plates = 840 - 280 = 56

9. Ans. D.

2004, $\frac{\text{Imports-Exports}}{\text{Exports}} = \frac{10}{7}$
 2005, $\frac{26}{76} = \frac{2}{7}$
 2006, $\frac{20}{100} = \frac{1}{5}$
 2007, $\frac{10}{100} = \frac{1}{11}$

10. Ans. B.

11. Ans. D.

Matrix multiplication is not commutative in general.

12. Ans. D.

Let E_1 = one children family
 E_2 = two children family
 A = picking a child then by Baye's theorem, required probability is

$$P\left(\frac{E_2}{A}\right) = \frac{\frac{1}{2} \cdot x}{\frac{1}{2} \cdot x + \frac{1}{2} \cdot x} = \frac{2}{3} = 0.667$$

(Here 'x' is number of families)

13. Ans. C.

$Z = -2j$ is a singularity lies inside $C: |Z| = 3$

∴ By Cauchy's integral formula,

$$\begin{aligned} \rightarrow \oint_C \frac{z^2 - z + 4j}{z + 2j} dz &= 2\pi j \cdot [z^2 - z + 4j]_{z=-2j} \\ &= 2\pi j [-4 + 2j + 4j] = 4\pi [3 + j2] \end{aligned}$$

14. Ans. A.

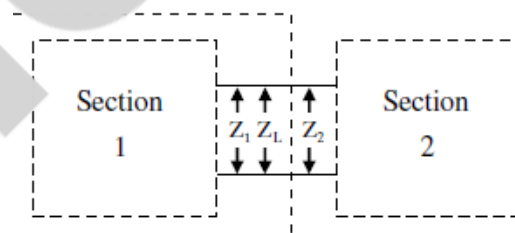
$A^2 = I \Rightarrow A = A^{-1} \Rightarrow \lambda$ is an eigen value of A then $\frac{1}{\lambda}$ is

also its eigen value. Since we require positive eigen value. ∴ $\lambda = 1$ is the only possibility as no other positive number is self inverse.

15. Ans. D.

16. Ans. C.

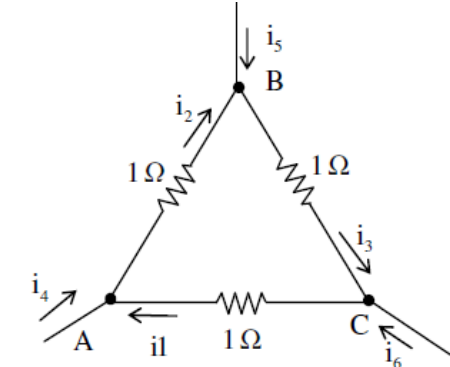
Two sections



Z_1 = Output impedance of first section
 Z_2 = Input impedance of second section
 For maximum power transfer, upto 1st section is

$Z_L = Z_1^*$
 $Z_L = Z_2 \Rightarrow Z_1^* = Z_2$

17. Ans. A.



Given $i_1 = 2A$

$$i_4 = -1A$$

$$i_5 = -4A$$

KCL at node A, $i_1 + i_4 = i_2$

$$\Rightarrow i_2 = 2 - 1 = 1A$$

1. KCL at node B, $i_2 + i_5 = i_3$

$$\Rightarrow i_3 = 1 - 4 = -3A$$

KCL at node C, $i_3 + i_6 = i_1$

$$\Rightarrow i_6 = 2 - (-3) = 5A$$

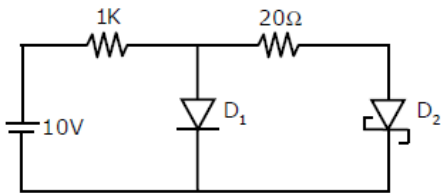
18. Ans. D.

$$\text{Responsivity } (R) = \frac{I_p}{P_0}$$

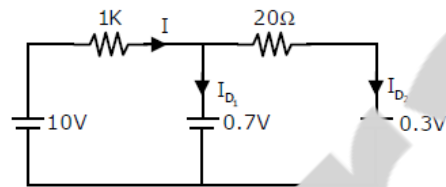
$$0.8 = \frac{I_p}{10 \times 10^{-6}}$$

$$\Rightarrow I_p = 8 \mu A$$

19. Ans. D.



Figure(1)



Assume both the diode ON.
Then circuit will be as per fig.

$$\therefore I = \frac{10 - 0.7}{1K}$$

$$I_{D_2} = \frac{0.7 - 0.3}{20} = 20 \mu A$$

$$\text{Now, } I_{D_1} = I - I_{D_2} = -10.7 \text{ mA (Not possible)}$$

$\therefore D_1$ is OFF and hence $D_2 - ON$

20. Ans. A.

21. Ans. B.

Ideal current Buffer has $Z_i = 0$

$$Z_o = \infty$$

22. Ans. B.

Output sample is voltage and is added at the input or current

\therefore It is voltage - shunt negative feedback i.e, voltage-current negative feedback

23. Ans. C.

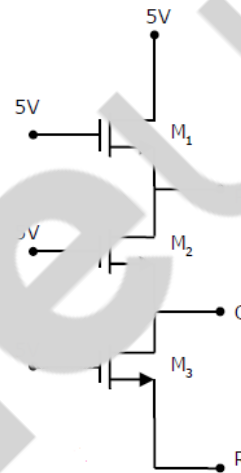
$$f = 5 \text{ KHz}$$

$$\text{Cut off frequency (LPF)} = \frac{1}{2\pi R_2 C} = 5 \text{ KHz}$$

$$\Rightarrow R_2 = \frac{1}{2\pi \times 5 \times 10^3 \times 10 \times 10^{-9}} = 2.18 \text{ k}\Omega$$

24. Ans. C.

Assume all NMOS are in saturation



$$\therefore V_{DS} \geq (V_{GS} - V_T)$$

For m_1

$$(5 - V_p) \geq (5 - V_p - 1)$$

$$(5 - V_p) > (4 - V_p) \Rightarrow \text{Sat}$$

$$\therefore I_{D_1} = k(V_{GS} - V_T)^2$$

$$I_{D_1} = K(4 - V_p)^2 \dots\dots\dots(1)$$

For m_2 ,

$$I_{D_1} = K(5 - V_Q - 1)^2$$

$$I_{D_1} = K(4 - V_Q)^2 \dots\dots\dots(2)$$

$$\therefore I_{D_1} = I_{D_2}$$

$$(4 - V_p)^2 = (4 - V_Q)^2$$

$$\Rightarrow V_p = V_Q \text{ \& } V_p = V_Q = 8$$

$$\Rightarrow V_p = V_Q = 4V$$

For m_3 ,

$$I_{D_3} = K(5 - V_R - 1)^2$$

$$\therefore I_{D_2} = I_{D_3}$$

$$(4 - V_Q)^2 = (4 - V_R)^2$$

$$\Rightarrow V_R = V_Q = 4V$$

$$\therefore V_P = V_Q = V_R = 4V$$

25. Ans. A.

Given Boolean Expression is $(X + Y)(X + \overline{Y})(X + \overline{\overline{Y}}) + \overline{X}$

As per the transposition theorem

$$(A + BC) = (A + B)(A + C)$$

$$\text{so, } (X + Y)(X + \overline{Y}) = X + Y\overline{Y} = X + 0$$

$$(X + Y)(X + \overline{Y})(X + \overline{\overline{Y}}) + \overline{X} = X + (\overline{X\overline{Y}}).X$$

$$= X + (\overline{X} + Y).X = X + \overline{X}X + Y.X = X + 0 + Y.X$$

$$\text{Apply absorption theorem} = X(1 + Y) = X.1 = X$$

26. Ans. C.

Given circuit is a Ripple (Asynchronous) counter. In this counter, o/p frequency of each flip-flop is half of the input frequency if their all the states are used otherwise.

o/p frequency of the counter is = $\frac{\text{input frequency}}{\text{modulus of the counter}}$

$$\text{So, the frequency at } Q_3 = \frac{\text{input frequency}}{16}$$

$$= \frac{1 \times 10^6}{16} \text{ Hz} = 62.5 \text{ kHz}$$

27. Ans. D.

Assume $x[n]$ to be periodic, with period N

$$\Rightarrow x[n] = x[n + N]$$

$$\Rightarrow \sin(\pi^2 n) = \sin(\pi^2(n + N))$$

Every trigonometric function repeats after 2π interval.

$$\Rightarrow \sin(\pi^2 n + \pi^2 N) = \sin(\pi^2 n)$$

$$\Rightarrow 2\pi k = \pi^2 N \quad (2\pi k = \pi^2 N)$$

Since 'k' is any integer, there is no possible value of 'k' for which 'N' can be an integer, thus non-periodic.

28. Ans. B.

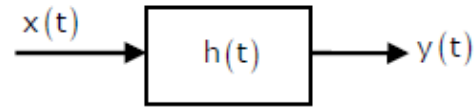
$x(t)$ is band limited to $[-500\text{Hz}, 500\text{Hz}]$ $y(t)$ is band limited to $[-1000\text{Hz}, 1000\text{Hz}]$ $z(t) = x(t) \cdot y(t)$

Multiplication in time domain results convolution in frequency domain.

The range of convolution in frequency domain is $[-1500\text{Hz}, 1500\text{Hz}]$

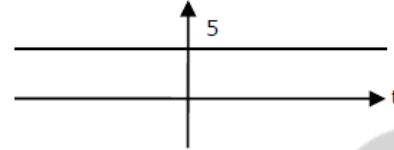
So maximum frequency present in $z(t)$ is 1500Hz Nyquist rate is 3000Hz or 3 kHz

29. Ans. C.

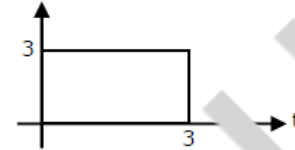


$$y(t) = x(t) * h(t)$$

$$x(t) =$$



$$h(t) =$$



$$y(t) = \int_0^3 5 \cdot 3 \, d\tau = 45 \text{ (steady state output)}$$

$$\text{Given } G(s) = \frac{K}{(s+2)(s-1)}$$

Characteristic equation: $1 + G(s)H(s) = 0$

$$1 + \frac{K}{(s+2)(s-1)} = 0$$

The poles are $s_{1,2} = -1 \pm \sqrt{\frac{9}{4} - 4K}$

$$\text{If } \frac{9}{4} - 4K = 0,$$

then both poles of the closed loop system at the same location.

$$\text{So, } K = \frac{9}{4} \Rightarrow 2.25$$

31. Ans. D.

For larger values of K, it will encircle the critical point $(-1 + j0)$, which makes closed-loop system unstable.

32. Ans. D.

$$\text{Spreading factor } (SF) = \frac{\text{chip rate}}{\text{symbol rate}}$$

This if a single symbol is represented by a code of 8 chips
Chip rate = $80 \times$ symbol rate

$$\text{S.F (Spreading Factor)} = \frac{8 \times \text{symbol rate}}{\text{symbol rate}} = 8$$

Spread factor (or) process gain and determine to a certain extent the upper limit of the total number of users supported simultaneously by a station.

33. Ans. A.

Capacity of channel is $1-H(p)$

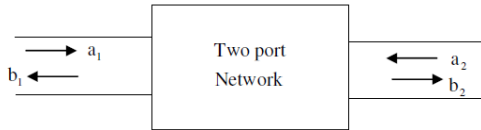
$H(p)$ is entropy function

With cross over probability of 0.5

$$H(p) = \frac{1}{2} \log_2 \frac{1}{0.5} + \frac{1}{2} \log_2 \frac{1}{0.5} = 1$$

$$\Rightarrow \text{Capacity} = 1 - 1 = 0$$

34. Ans. B.



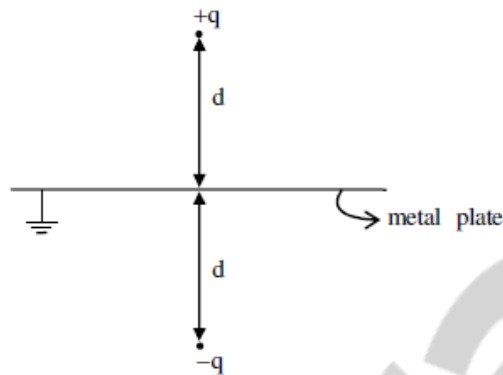
$$b_1 = s_{11}a_1 + s_{12}a_2$$

$$b_2 = s_{21}a_1 + s_{22}a_2$$

$$\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} s_{11} & s_{12} \\ s_{21} & s_{22} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}; S_{11} = \left. \frac{b_1}{a_1} \right|_{a_2=0}$$

By verification Answer B satisfies.

35. Ans. C.



$$F = \frac{1}{4\pi\epsilon} \frac{Q_1 Q_2}{R^2}$$

$$F = \frac{1}{4\pi\epsilon} \frac{q^2}{(2d)^2} = \frac{q^2}{16\pi\epsilon d^2}$$

Since the charges are of opposite polarity the force between them is attractive.

36. Ans. A.

$$3\sin x + 2\cos x = 3\left(x - \frac{x^3}{3!} + \dots\right) + 2\left(x - \frac{x^2}{2!} + \dots\right)$$

$$= 2 + 3x - x^2 - \frac{x^3}{2} + \dots$$

37. Ans. B.

Given

$$\int_{-\infty}^{\infty} g(t).e^{j\omega t} dt = \omega^{-2} (let G(j\omega))$$

$$\Rightarrow \int_{-\infty}^{\infty} g(t) dt = 0$$

$$y(t) = \int_{-\infty}^t g(z).dz \Rightarrow y(t) = g(t) * u(t)$$

[$u(t)$ in unit step function]

$$\Rightarrow Y(j\omega) = G(j\omega).U(j\omega)$$

$$Y(j\omega) = \int_{-\infty}^{\infty} y(t).e^{-j\omega t} dt$$

$$\Rightarrow Y(j0) = \int_{-\infty}^{\infty} y(t).e^{-j0t} dt$$

$$= \left[\omega.e^{-2\omega^2} \left[\frac{1}{j\omega} + \pi\delta(\omega) \right] \right]_{\omega=0} = 0$$

$$= \frac{1}{j} = -j$$

38. Ans. D.

$$\text{Volume} = \int_R \int_R (x,y) dy dx = \int_{x=0}^x \int_{y=0}^x (x+y) dy dx$$

$$= \int_0^{12} \left[\frac{1}{2}x^2 + y^2 \right]_0^x dx = \int_0^{12} \frac{3}{2}x^2 dx = \frac{3}{2} \left[\frac{x^3}{3} \right]_0^{12} = 864$$

39. Ans. B.

Consider, (i) Let $P = I_2 + \alpha J_2$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \alpha \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & \alpha \\ \alpha & 1 \end{bmatrix}$$

$$\Rightarrow |P| = 1 - \alpha^2$$

$$(ii) \text{ Let } P = I_4 + \alpha J_4 = \begin{bmatrix} 1 & 0 & 0 & \alpha \\ 0 & 1 & \alpha & 0 \\ 0 & \alpha & 1 & 0 \\ \alpha & 0 & 0 & 1 \end{bmatrix}$$

$$|P| = (1) \begin{vmatrix} 1 & \alpha & 0 \\ \alpha & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} - (\alpha) \begin{vmatrix} 0 & 1 & \alpha \\ \alpha & 1 & 0 \\ \alpha & 0 & 0 \end{vmatrix}$$

$$= (1 - \alpha^2) - (\alpha) [\alpha(1 - \alpha^2)] = (1 - \alpha^2)^2$$

Similarly, if $P = I_6 + \alpha J_6$ then we get

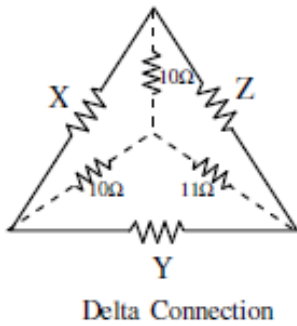
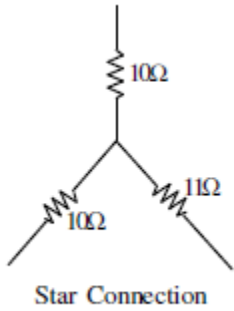
$$|P| = (1 - \alpha^2)^3$$

$$|P| = 0 \Rightarrow \alpha = -1, 1$$

\therefore negative

$$\therefore \alpha = 1$$

40. Ans. D.



$$x = 29.09\Omega, y = 32\Omega, z = 32\Omega$$

$$x = \frac{(10)(10) + (10)(11) + (10)(11)}{11} \Omega$$

$$y = \frac{(10)(10) + (10)(11) + (10)(11)}{10} \Omega$$

$$z = \frac{(10)(10) + (10)(11) + (10)(11)}{10} \Omega$$

i.e, lowest value among three resistances is 29.09Ω

41. Ans. B.

Load 1:

$$P = 10 \text{ kW}$$

$$\cos \phi = 0.8 \Rightarrow S_1 = P - jQ = 10 - j7.5 \text{ KVA}$$

$$Q = P \tan \phi = 7.5 \text{ KVAR}$$

Load 2: $S = 10 \text{ KVA}$

$$\cos \phi = 0.8 \Rightarrow S_2 = 10 \text{ KVA}$$

$$\cos \phi = \frac{P}{S}$$

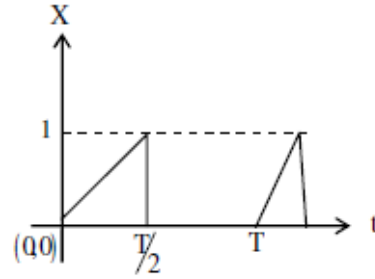
$$0.8 = \frac{P}{10} \Rightarrow 8 \text{ kW} \quad Q = 6 \text{ KVAR}$$

$$S_1 + S_2 = 8 + j6 + 10 = 18 + j6 \text{ KVA}$$

Complex power delivered by the source is

$$S_1 + S_2 = 18 - j1.5 \text{ KVA}$$

42. Ans. C.



$$x_{rms} = \sqrt{\frac{1}{T} \int_0^T (x(t))^2 dt}$$

$$x(t) = \begin{cases} \frac{2}{T}t & 0 \leq t \leq T/2 \\ 0 & T/2 \leq t \leq T \end{cases}$$

$$= \sqrt{\frac{1}{T} \left[\int_0^{T/2} \left(\frac{2}{T}t\right)^2 dt + \int_{T/2}^T (0)^2 dt \right]}$$

$$= \sqrt{\frac{1}{T} \left[\frac{4}{3T^3} t^3 \right]_0^{T/2}}$$

$$x_{rms} = \sqrt{\frac{4}{3T^3} \cdot \frac{T^3}{8}} \Rightarrow \sqrt{\frac{1}{6}} \Rightarrow 0.408$$

43. Ans. B.

By KVL,

$$v(t) = Ri(t) + L \frac{di(t)}{dt} + \frac{1}{C} \int i(t) dt$$

Differentiate with respect to time,

$$0 = \frac{R \cdot di(t)}{dt^2} + \frac{R}{L} \cdot \frac{di(t)}{dt} + \frac{i(t)}{LC} = 0$$

$$\frac{d^2 i(t)}{dt^2} + \frac{R}{L} \frac{di(t)}{dt} + \frac{i(t)}{LC} = 0$$

$$D_{1,2} = \frac{-R/L \pm \sqrt{\left(\frac{R}{L}\right)^2 - \frac{4}{LC}}}{2}$$

$$D_{1,2} = \frac{-R}{L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}$$

For critically damped response,

$$\left(\frac{R}{2L}\right)^2 = \frac{1}{LC} \Rightarrow C = \frac{4L}{R^2} F$$

Given, $L = 4H$; $R = 40\Omega$

$$C = \frac{4 \times 4}{(40)^2} \Rightarrow 10 \text{ mF}$$

44. Ans. D.

$$V_{BE} = 0.7V, \frac{KT}{q} = 25mV, I_s = 10^{-13}$$

Transconductance, $g_m = \frac{I_C}{V_T}$

$$I_C = I_s [e^{V_{BE}/V_T} - 1]$$

$$= 10^{-13} [e^{0.7/25mV} - 1] = 144.625mA$$

$$\therefore g_m = \frac{I_C}{V_T} = \frac{144.625mA}{25mV} = 5.785A/V$$

45. Ans. A.

Electron concentration, $n \approx$

$$= \frac{(1.5 \times 10^{10})^2}{1 \times 10^{16}} e^{0.3/26mV}$$

$$= 2.3 \times 10^9 / cm^3$$

46. Ans. C.

Given $V_T = -0.5V; V_{GS} = 2V; V_{DS} = 5V;$

$W/L = 100; C_{ox} = 10^{-8} f/cm$

$\mu_n = 800cm^2 / v - s$

$$I_D = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} [2(V_{GS} - V_T)V_{DS} - V_{DS}^2]$$

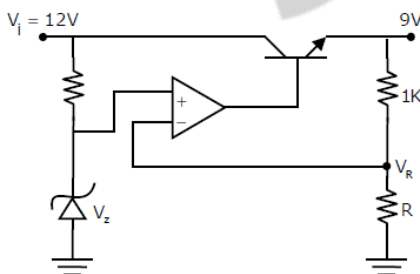
$$\left[\frac{\partial I_D}{\partial V_{DS}} \right]^{-1} = r_{ds} \left[\frac{\partial}{\partial V_{DS}} \left\{ \frac{1}{2} \mu_n C_{ox} \frac{W}{L} [2(V_{GS} - V_T)V_{DS} - V_{DS}^2] \right\} \right]^{-1}$$

$$= \left[\mu_n C_{ox} \frac{W}{L} (V_{GS} - V_T) - \mu_n C_{ox} \frac{W}{L} V_{DS} \right]^{-1}$$

$$\Rightarrow |r_{ds}| = \left| \frac{1}{\mu_n C_{ox} \frac{W}{L} (V_{GS} - V_T) - \mu_n C_{ox} \frac{W}{L} V_{DS}} \right|$$

$$= \left| \frac{1}{800 \times 10^{-8} \times 100 \times (2 - 5)} \right| = 100\Omega$$

47. Ans. C.



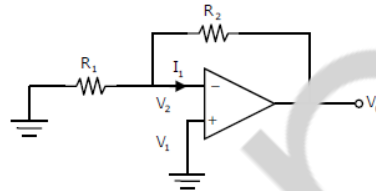
Given $V_{BE} = 0.7V, \beta = 100, V_Z = 4.7V, V_0 = 9V$

$$V_R = 9 \times \frac{R}{R + 1k}$$

$$4.7 = 9 \times \frac{R}{R + 1k} (\because \quad)$$

$$R = 1093\Omega$$

48. Ans. C.



Given, $Z_i = \infty$

$A_{0L} = \infty$

$V_{i0} = 0$

$V_2 = (R_1 // R_2) I_1$

$$\frac{V_2}{R_1 // R_2} = I_1 \dots (1)$$

at inverting node

$$\frac{V_2}{R_1} + \frac{V_2}{R_2} = 0 (\because Z_i = \infty)$$

$$\frac{V_2}{R_2} = V_2 \left[\frac{1}{R_1} + \frac{1}{R_2} \right]$$

$$\frac{V_0}{R_2} = \left(\frac{R_1 R_2}{R_1 + R_2} \right) I_1 \left[\frac{R_2 + R_1}{R_1 R_2} \right]$$

$$\Rightarrow V_0 = I_1 R_2$$

49. Ans. D.

$V_{BE} = 0.7V, \beta = 200, V_T = 25mV$

DC Analysis:

$$V_B = 12 \times \frac{1k}{1k + 33k} = 3V$$

$$V_E = 3 - 0.7 = 2.3V$$

$$I_E = \frac{2.3}{10 + 1k} = 2.277mA$$

$$I_B = 11.34\mu A$$

$$I_C = 2.26mA$$

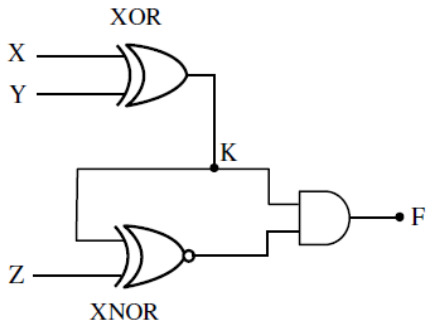
$$r_e = \frac{25mV}{2.277mA} = 10.98\Omega$$

$$A_v = \frac{V_0}{V_i} = \frac{-\beta R_C}{\beta r_e + (1 + \beta)(R_s)}$$

$$= \frac{-200 \times 5k}{200 \times 10.98 + (201)10}$$

$$A_v = -237.76$$

50. Ans. A.



Assume dummy variable K as a output of XOR gate

$$K = X \oplus Y = \overline{X}Y + X\overline{Y}$$

$$F = K \cdot (K \odot Z)$$

$$= (\overline{K}Z + K.Z)$$

$$= K \cdot \overline{K}Z + K.K.Z$$

$$= 0 + K.Z (\because \overline{K}K = 0 \text{ and } K.K = K)$$

Put the value of K in above expression

$$F = (\overline{X}Y + X\overline{Y})Z$$

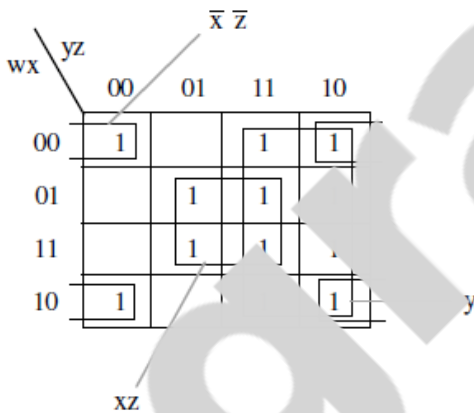
$$= \overline{X}YZ + X\overline{Y}Z$$

51. Ans. D.

Given Boolean Function is

$$F(w, x, y, z) = wy + xy + \overline{w}xyz + \overline{w}xy + xz + \overline{w}xyz.$$

By using K-map



So, the essential prime implicants (EPI) are $y, xz, \overline{w}z$

52. Ans. D.

The input of D_2 flip-flop is

$$D_2 = \overline{Q}_1S + Q_1\overline{S} (\because)$$

The alternate expression for EX-NOR gate is

$$= \overline{A \oplus B} = \overline{A \oplus B} = A \oplus \overline{B}$$

So, if the Ex-OR gate is substituted by Ex-NOR gate then

input A should be connected to \overline{Q}_1

$$D_2 = \overline{Q}_1\overline{S} + Q_1S = \overline{Q}_1\overline{S} + \overline{Q}_1.S (\because)$$

$$= Q_1\overline{S} + \overline{Q}_1.S$$

53. Ans. C.

$$\text{Given } x[n] = \left(\frac{1}{-9}\right)^n u(n) - \left(-\frac{1}{3}\right)^n u[-n-1]$$

$$\text{for } \left(\frac{-1}{9}\right)^n u[n] R_{oc} \text{ in } |z| > \frac{1}{9}$$

(Right sided sequence, R_{oc} in exterior of circle of radius $\frac{1}{9}$)

$$\text{Thus overall } R_{oc} \text{ in } \frac{1}{9} < |z| < \frac{1}{3}$$

54. Ans. B.

$$\text{Given } x[n] = \sin\left(\frac{\pi n}{10}\right); N = 10$$

\Rightarrow Fourier series coefficients are 2π periodic with period $N = 10$

$$x[n] = \frac{1}{2j} e^{j\frac{\pi n}{10}} - \frac{1}{2j} e^{-j\frac{\pi n}{10}} = a_{-1} + 20$$

$$a_{-1} = \frac{1}{2j}, a_{-1+10} = \frac{-1}{2j} \Rightarrow a_{-1} = a_{-1+10} = a_9 = \frac{-1}{2j}$$

$$a_{-1+10} = a_9 = a_1 + 20$$

$$a_1 = a_{-1} + 20 \text{ or } a_{-1} = a_{-1} + 20$$

$$\Rightarrow k = 10m + 1 \text{ or } k = 10.m - 1 \Rightarrow B = 10$$

55. Ans. A.

Given $y'(t) + 5y(t) = u(t)$ and $y(0) = 1$; $u(t)$ is a unit step function.

Apply Laplace transform to the given differential equation.

$$sY(s) - y(0) + 5Y(s) = \frac{1}{s}$$

$$y(s)[s+5] = \frac{1}{s} + y(0) \left[L \left[\frac{dy}{dt} \right] = sy(s) - y(0) \right]$$

$$\left[L[u(t) = 1/s] \right]$$

$$y(s) = \frac{\frac{1}{s} + 1}{(s+5)}$$

$$y(s) = \frac{\frac{1}{s} + 1}{(s+5)} \Rightarrow \frac{A}{s} + \frac{B}{s+5}$$

$$A = 1/5; B = 4/5$$

$$y(s) = \frac{1}{5s} + \frac{4}{5(s+5)}$$

Apply inverse Laplace transform,

$$y(t) = \frac{1}{5} + \frac{4}{5} e^{-5t}$$

$$y(t) = 0.2 + 0.8e^{-5t}$$

56. Ans. B.

From the given state model,

$$A = \begin{bmatrix} -1 & 1 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -2 \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 4 \\ 0 \end{bmatrix} \quad C = [1 \ 1 \ 1]$$

Controllable: $Q_c = c = [B \ AB \ A^2B]$

if $|Q_c| \neq 0 \rightarrow$ controllable

$$Q_c = \begin{bmatrix} 0 & 4 & -8 \\ 4 & -4 & 4 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow |Q_c| = 0$$

\therefore uncontrollable

Observable: $Q_0 = \begin{bmatrix} C \\ CA \\ CA^2 \end{bmatrix}$

If $|Q_0| \neq 0 \rightarrow$ observable

$$Q_0 = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & -2 \\ 1 & 2 & 4 \end{bmatrix} \Rightarrow |Q_0| = 1$$

\therefore Observable

The system is uncontrollable and observable

57. Ans. D.

$$G(s) = \frac{10}{(s+0.1)(s+1)(s+10)}$$

$$G(s) = \frac{10}{0.1 \left[1 + \frac{s}{0.1}\right] \left[1 + s\right] \left[1 + \frac{s}{10}\right]}$$

$$G(s) = \frac{10}{[1+10s][1+s][1+\frac{s}{10}]}$$

By Approximation, $\phi(\omega) = \frac{180}{[10s]}$

Phase Margin = $180^\circ - \phi(\omega)$

$$\omega_{gc} = 1 = \frac{1}{\sqrt{100\omega}}$$

$$= 180 - \tan^{-1}\left(\frac{10 \times 0.99}{1}\right)$$

$$= 100\omega^2 = \frac{99}{1\omega}$$

$$\text{Phase Margin} = 95^\circ.73$$

$$\Rightarrow \omega^2 \frac{\sqrt{99}}{1\omega} \Rightarrow \omega_{gc} = 0.9949r / sc$$

Asymptotic approximation, Phase margin = $\phi - 45^\circ = 48$

58. Ans. C.

By observing the options, if we place other options, characteristic equation will have 3rd order one, where we cannot describe the settling time.

If $C(s) = 2(s+4)$ is considered

The characteristic equation, is

$$s^2 + 3s + 2 + 2s + 8 = 0$$

$$\Rightarrow s^2 + 5s + 10 = 0$$

Standard character equation $s^2 + 2\xi\omega_n s + \omega_n^2 = 0$

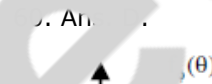
$$\omega_n^2 = \sqrt{10}; \xi\omega_n = 2.5$$

Given, 2% settling time, $\frac{4}{\xi\omega_n} < 2 \Rightarrow \xi\omega_n > 2$

59. Ans. B.

$V(x) = E(x^2) - \{E(x)\}^2 \geq 0$. Variance cannot be negative

$$\therefore E(x^2) \geq \{E(x)\}^2$$



Given $X(t) = \sqrt{2} \sin(2\pi t + \phi)$

ϕ in uniformly distributed in the interval $[0, 2\pi]$

$$E[x(t_1)x(t_2)]$$

$$= \int_0^{2\pi} \sqrt{2} \sin(2\pi t_1 + \theta) \sqrt{2} \sin(2\pi t_2 + \theta) f_\phi(\theta) d\theta$$

$$= 2 \int_0^{2\pi} \sin(2\pi t_1 + \theta) \sin(2\pi t_2 + \theta) \cdot \frac{1}{2\pi} d\theta$$

$$= \frac{1}{2\pi} \int_0^{2\pi} \sin(2\pi(t_1 + t_2) + 2\theta) d\theta$$

$$+ \frac{1}{2\pi} \int_0^{2\pi} \cos(2\pi(t_1 - t_2) + 2\theta) d\theta$$

First integral will result into zero as we are integrating from 0 to 2π .

Second integral result into $\cos\{2\pi(t_1 - t_2)\}$

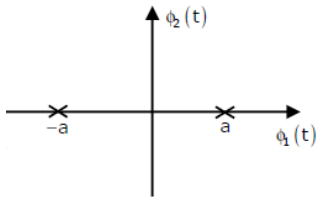
$$\Rightarrow E[X(t_1)X(t_2)] = \cos(2\pi(t_1 - t_2))$$

61. Ans. C.

Bit error rate for BPSK

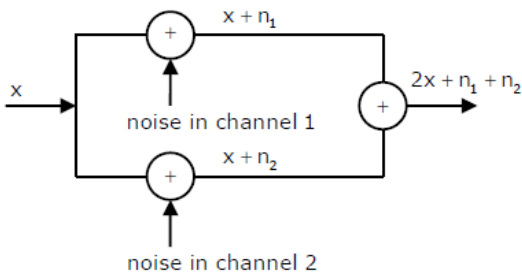
$$= Q\left(\sqrt{\frac{2E}{N_0}}\right) \cdot \left\{ Q\left[\sqrt{\frac{E}{N_0/2}}\right] \right\}$$

$$\Rightarrow Y = \frac{2E}{N_0}$$



Function of bit energy and noise $P_{SD} \frac{N_0}{2}$

Constellation diagram of BPSK
Channel is A_{WGN} which implies noise sample as independent



Let $2x + n_1 + n_2 = x^1 + n^1$

where $x^1 = 2x$

$n^1 = n_1 + n_2$

Now Bit error rate = $Q\left(\sqrt{\frac{2E}{N_0}}\right)$

E^1 is energy in x^1

N_0^1 is PSD of n^1

$E^1 = 4E$ [as amplitudes are doubled]

$N_0^1 = N_0$ [independent noise in each channel]

\Rightarrow Bit error rate = $Q\left(\sqrt{\frac{4E}{N_0}}\right) = Q\left(\sqrt{2} \sqrt{\frac{2E}{N_0}}\right)$

$\Rightarrow b = \sqrt{2}$ or 1.414

62. Ans. B.

In this problem random variable is L

L can be 1, 2,

$P\{L=1\} = \frac{1}{2}$

$P\{L=3\} = \frac{1}{8}$

$H\{L\} = \frac{1}{2} \log_2 \frac{1}{1/2} + \frac{1}{4} \log_2 \frac{1}{1/4} + \frac{1}{8} \log_2 \frac{1}{1/8} + \dots$
 $= 0 + 1 \cdot \frac{1}{2} + 2 \cdot \frac{1}{4} + 3 \cdot \frac{1}{8} + \dots$

[Arithmetic geometric series summation]

$= \frac{2}{1 - 1/2} + \frac{1/2 \cdot 1}{(1 - 1/2)^2} = 2$

63. Ans. B.

$E_\theta = \frac{100}{r} \sin \theta e^{-j\beta r}$

$E_\phi = \frac{100}{r} \cos \theta \sin \theta e^{-j\beta r}$

$E_{avg} = \frac{1}{2} \int_0^{2\pi} \int_0^\pi I_Q^* ds$

$= \frac{1}{2} \int_0^{2\pi} \int_0^\pi \frac{(0.265)}{r^2} \sin^2 \theta r^2 \sin \theta d\theta d\phi$

$E_{avg} = \frac{1}{2} \int_0^{2\pi} \int_0^\pi (26.5) \sin^2 \theta d\theta d\phi$

$= 13.25 \int_{\theta=0}^{\pi/2} \sin^3 \theta d\theta \int_{\phi=0}^{2\pi} d\phi = 13.25 \left(\frac{2}{3}\right) (2\pi)$

$P = 55.5 w$

64. Ans. B.

$Z_0 = \frac{276}{\sqrt{\epsilon_r}} \log\left(\frac{d}{r}\right)$

d → distance between the two plates

so, z_0 - changes, if the spacing between the plates changes.

$V = \frac{1}{\sqrt{LC}} \rightarrow$ independent of spacing between the plates

65. Ans. B.

Given, $l = \lambda/8$

$Z_0 = 50\Omega$

$Z_{in}(l = \lambda/8) = Z_0 \left[\frac{Z_L + jZ_0}{Z_0 + jZ_L} \right]$

$$Z_{in} = 50 \left[\frac{Z_L + J50}{50 + JZ_L} \right] = 50 \left[\frac{Z_L + J50}{50 + JZ_L} \times \frac{50 - JZ_L}{50 - JZ_L} \right]$$
$$Z_{in} = 50 \left[\frac{50Z_L + 50Z_L + J(50^2 - Z_L^2)}{50^2 + Z_L^2} \right]$$

Given, $Z_{in} \rightarrow$ Real

So, $I_{mg}(Z_{in}) = 0$

$$50^2 - Z_L^2 = 0$$

$$Z_L^2 = 50^2$$

$$R^2 + X^2 = 50^2$$

$$R^2 = 50^2 - X^2 = 50^2 - 30^2$$

$$R = 40\Omega$$

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